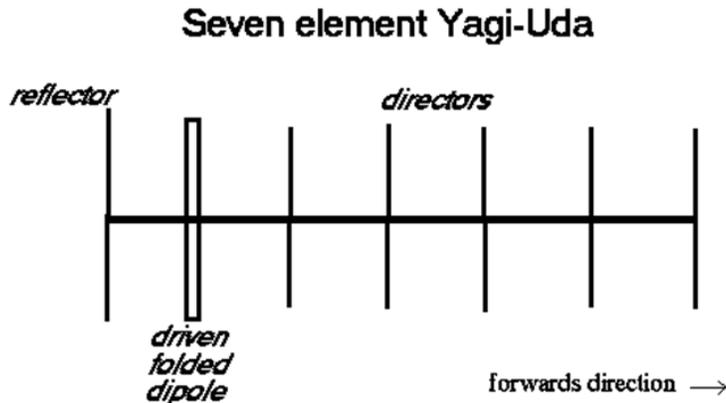


# YAGI UDA ARRAY

Yagi-Uda or Yagi is named after the inventors Prof. S.Uda and Prof. H.Yagi around 1928.

The basic element used in a Yagi is  $\lambda/2$  dipole placed horizontally known as driven element or active element. In order to convert bidirectional dipole into unidirectional system, the passive elements are used which include reflector and director. The passive or parasitic elements are placed parallel to driven element, collinearly placed close together as shown in fig 6.4.

The Parasitic element placed in front of driven element is called director whose length is 5% less than the drive element. The element placed at the back of driven element is called reflector whose length is 5% more than that of driver element. The space between the element ranges between  $0.1\lambda$  to  $0.3\lambda$ .



For a three element system,

Reflector length =  $500/f$  (MHz) feet

Driven element length =  $475/f$  (MHz) feet

Director length =  $455/f$  (MHz) feet.

The above relations are given for elements with length to diameter ratio between 200 to 400 and spacing between  $0.1\lambda$  to  $0.2\lambda$ .

With parasitic elements the impedance reduces less than  $73\ \Omega$  and may be even less than  $25\ \Omega$ . A folded  $\lambda/2$  dipole is used to increase the impedance.

System may be constructed with more than one director. Addition of each director increases the gain by nearly 3 dB. Number of elements in a yagi is limited to 11.

## **Basic Operation:**

The phases of the current in the parasitic element depends upon the length and the distance between the elements. Parasitic antenna in the vicinity of radiating antenna is used either to reflect or to direct the radiated energy so that a compact directional system is obtained.

A parasitic element of length greater than  $\lambda/2$  is inductive which lags and of length less than  $\lambda/2$  is capacitive which leads the current due to induced voltage. Properly spaced elements of length less than  $\lambda/2$  act as director and add the fields of driven element. Each director will excite the next. The reflector adds the fields of driven element in the direction from reflector towards the driven element.

The greater the distance between driven and director elements, the greater the capacitive reactance needed to provide correct phasing of parasitic elements. Hence the length of element is tapered-off to achieve reactance.

A Yagi system has the following characteristics.

1. The three element array (reflector, active and director) is generally referred as “beam antenna”
2. It has unidirectional beam of moderate directivity with light weight, low cost and simplicity in design.
3. The band width increases between 2% when the space between elements ranges between  $0.1\lambda$  to  $0.15\lambda$ .
4. It provides a gain of 8 dB and a front-to-back ratio of 20dB.
5. Yagi is also known as super-directive or super gain antenna since the system results a high gain.
6. If greater directivity is to be obtained, more directors are used. Array up to 40 elements can be used.
7. Arrays can be stacked to increase the directivity.
8. Yagi is essentially a fixed frequency device. Frequency sensitivity and bandwidth of about 3% is achievable.
9. To increase the directivity Yagi's can be staked one above the other or one by side of the other.