

PSEUDO NMOS LOGIC

This logic structure consists of the pull up circuit being replaced by a single pull up pmos whose gate is permanently grounded. This actually means that pmos is all the time on and that now for a n input logic we have only n+1 gates. This technology is equivalent to the depletion mode type and preceded the CMOS technology and hence the name pseudo. The two sections of the device are now called as load and driver. The G_n/G_p (G_{driver}/G_{load}) has to be selected such that sufficient gain is achieved to get consistent pull up and pull down levels. This involves having ratioed transistor sizes so that correct operation is obtained. However if minimum size drivers are being used then the gain of the load has to be reduced to get adequate noise margin.

There are certain drawbacks of the design which is highlighted next

1. The gate capacitance of CMOS logic is two unit gates but for pseudo logic it is only one gate unit.
2. Since number of transistors per input is reduced area is reduced drastically.

The disadvantage is that since the pMOS is always on, static power dissipation occurs whenever the nmos is on. Hence the conclusion is that in order to use pseudo logic a tradeoff between size & load or power dissipation has to be made.

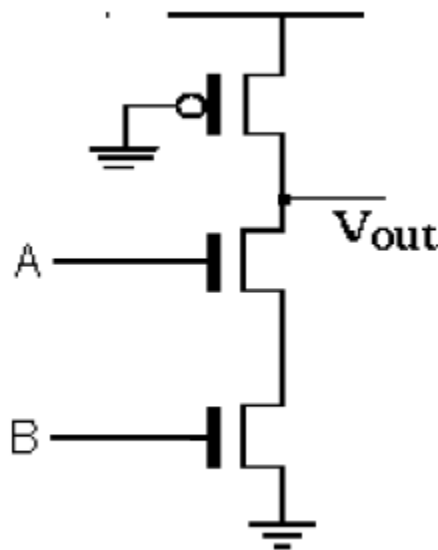


Figure 3: Pseudo Nmos

3.4.1 OTHER VARIATIONS OF PSEUDO NMOS

1. Multi drain logic

One way of implementing pseudo nmos is to use multi drain logic. It represents a merged transistor kind of implementation. The gates are combined in an open drain manner, which is useful in some automated circuits. Figure 4.

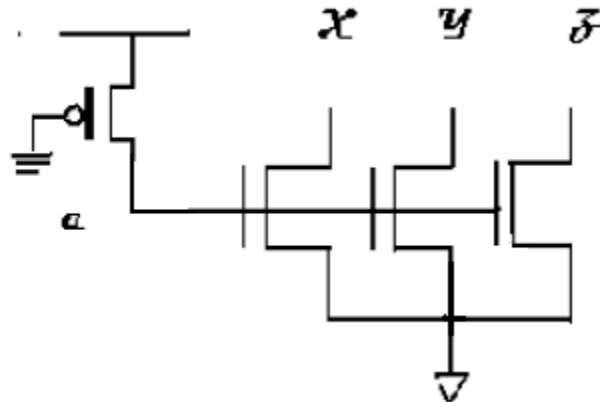
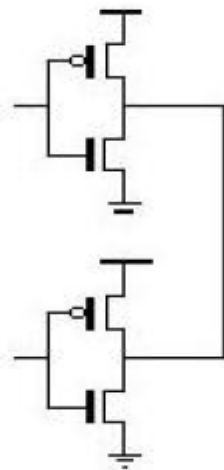


Figure 4: Multi drain logic.

3.4.2 GANGED LOGIC



The inputs are separately connected but the output is connected to a common terminal. The logic depends on the pull up and pull down ratio. If pmos is able to overcome nmos it behaves as nand else nor.