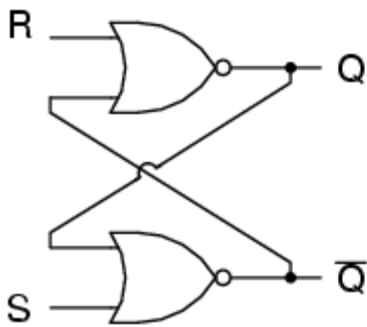


# The S-R latch

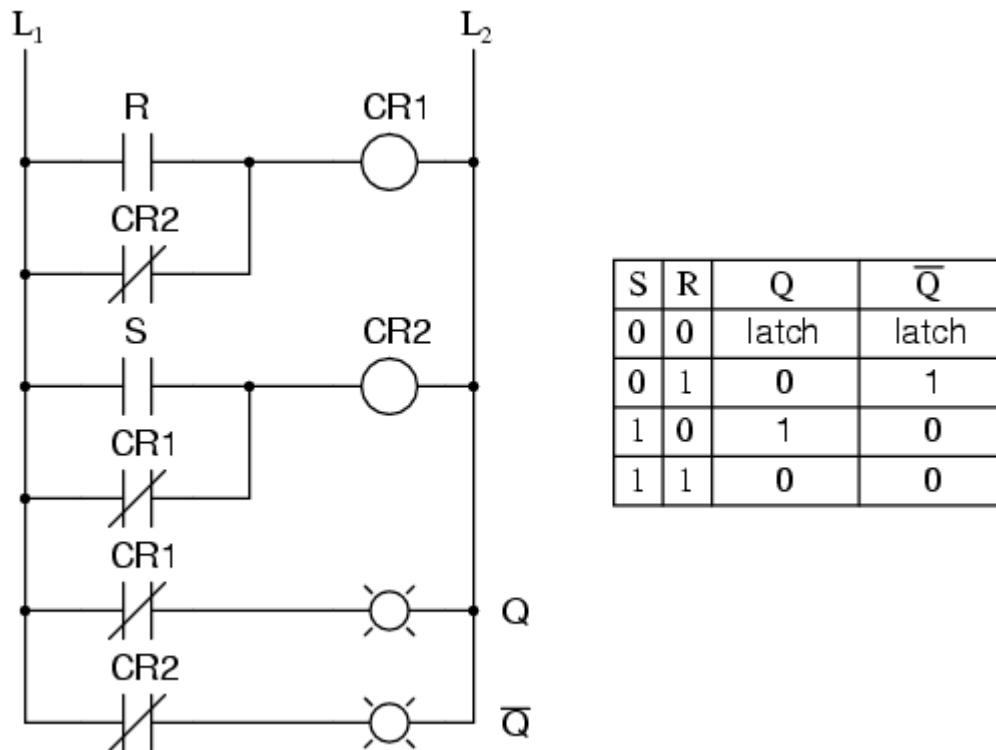
A bistable multivibrator has *two* stable states, as indicated by the prefix *bi* in its name. Typically, one state is referred to as *set* and the other as *reset*. The simplest bistable device, therefore, is known as a *set-reset*, or S-R, latch.

To create an S-R latch, we can wire two NOR gates in such a way that the output of one feeds back to the input of another, and vice versa, like this:



S	R	Q	$\bar{Q}$
0	0	latch	latch
0	1	0	1
1	0	1	0
1	1	0	0

The Q and not-Q outputs are supposed to be in opposite states. I say "supposed to" because making both the S and R inputs equal to 1 results in both Q and not-Q being 0. For this reason, having both S and R equal to 1 is called an *invalid* or *illegal* state for the S-R multivibrator. Otherwise, making S=1 and R=0 "sets" the multivibrator so that Q=1 and not-Q=0. Conversely, making R=1 and S=0 "resets" the multivibrator in the opposite state. When S and R are both equal to 0, the multivibrator's outputs "latch" in their prior states. Note how the same multivibrator function can be implemented in ladder logic, with the same results:



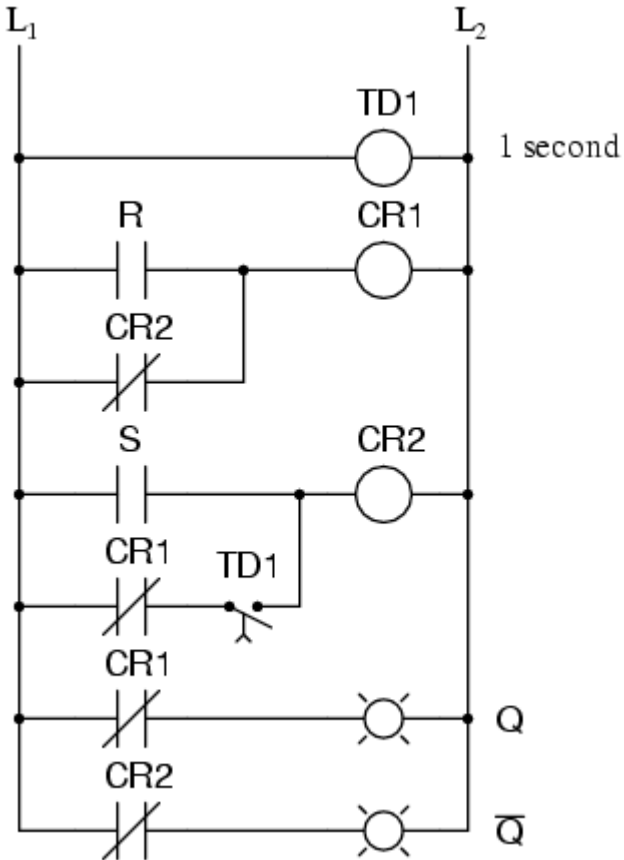
By definition, a condition of  $Q=1$  and  $\text{not-}Q=0$  is *set*. A condition of  $Q=0$  and  $\text{not-}Q=1$  is *reset*. These terms are universal in describing the output states of any multivibrator circuit.

The astute observer will note that the initial power-up condition of either the gate or ladder variety of S-R latch is such that both gates (coils) start in the de-energized mode. As such, one would expect that the circuit will start up in an invalid condition, with both Q and not-Q outputs being in the same state. Actually, this is true! However, the invalid condition is unstable with both S and R inputs inactive, and the circuit will quickly stabilize in either the set or reset condition because one gate (or relay) is bound to react a little faster than the other. If both gates (or coils) were *precisely identical*, they would oscillate between high and low like an astable multivibrator upon power-up without ever reaching a point of stability! Fortunately for cases like this, such a precise match of components is a rare possibility.

It must be noted that although an astable (continually oscillating) condition would be extremely rare, there will most likely be a cycle or two of oscillation in the above circuit, and the final state of the circuit (set or reset) after power-up would be unpredictable. The root of the problem is a *race condition* between the two relays  $CR_1$  and  $CR_2$ .

A race condition occurs when two mutually-exclusive events are simultaneously initiated through different circuit elements by a single cause. In this case, the circuit elements are relays  $CR_1$  and  $CR_2$ , and their de-energized states are mutually exclusive due to the normally-closed interlocking contacts. If one relay coil is de-energized, its normally-closed contact will keep the other coil energized, thus maintaining the circuit in one of two states (set or reset). Interlocking prevents *both* relays from latching. However, if *both* relay coils start in their de-energized states (such as after the whole circuit has been de-energized and is then powered up) both relays will "race" to become latched on as they receive power (the "single cause") through the normally-closed contact of the other relay. One of those relays will inevitably reach that condition before the other, thus opening its normally-closed interlocking contact and de-energizing the other relay coil. Which relay "wins" this race is dependent on the physical characteristics of the relays and not the circuit design, so the designer cannot ensure which state the circuit will fall into after power-up.

Race conditions should be avoided in circuit design primarily for the unpredictability that will be created. One way to avoid such a condition is to insert a time-delay relay into the circuit to disable one of the competing relays for a short time, giving the other one a clear advantage. In other words, by purposely slowing down the de-energization of one relay, we ensure that the other relay will always "win" and the race results will always be predictable. Here is an example of how a time-delay relay might be applied to the above circuit to avoid the race condition:

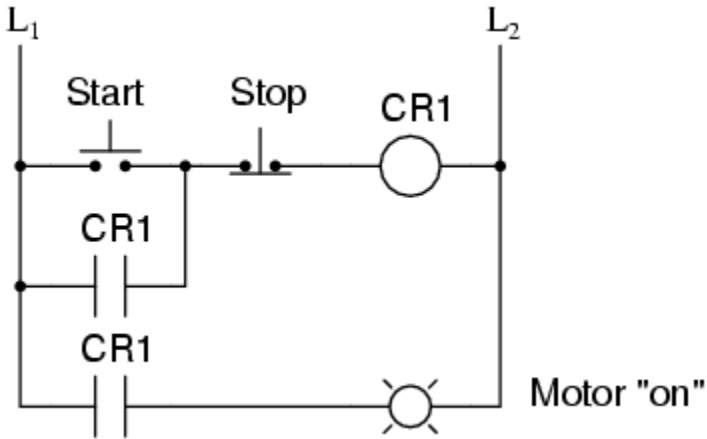


When the circuit powers up, time-delay relay contact  $TD_1$  in the fifth rung down will delay closing for 1 second. Having that contact open for 1 second prevents relay  $CR_2$  from energizing through contact  $CR_1$  in its normally-closed state after power-up. Therefore, relay  $CR_1$  will be allowed to energize first (with a 1-second head start), thus opening the normally-closed  $CR_1$  contact in the fifth rung, preventing  $CR_2$  from being energized without the  $S$  input going active. The end result is that the circuit powers up cleanly and predictably in the reset state with  $S=0$  and  $R=0$ .

It should be mentioned that race conditions are not restricted to relay circuits. Solid-state logic gate circuits may also suffer from the ill effects of race conditions if improperly designed. Complex computer programs, for that matter, may also incur race problems if improperly designed. Race problems are a possibility for any sequential system, and may not be discovered until some time after initial testing of the system. They can be very difficult problems to detect and eliminate.

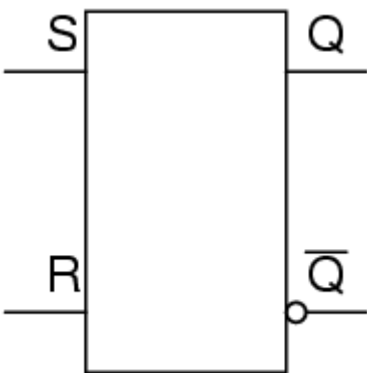
A practical application of an S-R latch circuit might be for starting and stopping a motor, using normally-open, momentary pushbutton switch contacts for

both *start* (S) and *stop* (R) switches, then energizing a motor contactor with either a CR<sub>1</sub> or CR<sub>2</sub> contact (or using a contactor in place of CR<sub>1</sub> or CR<sub>2</sub>). Normally, a much simpler ladder logic circuit is employed, such as this:



In the above motor start/stop circuit, the CR<sub>1</sub> contact in parallel with the *start* switch contact is referred to as a "seal-in" contact, because it "seals" or latches control relay CR<sub>1</sub> in the energized state after the *start* switch has been released. To break the "seal," or to "unlatch" or "reset" the circuit, the *stop* pushbutton is pressed, which de-energizes CR<sub>1</sub> and restores the seal-in contact to its normally open status. Notice, however, that this circuit performs much the same function as the S-R latch. Also note that this circuit has no inherent instability problem (if even a remote possibility) as does the double-relay S-R latch design.

In semiconductor form, S-R latches come in prepackaged units so that you don't have to build them from individual gates. They are symbolized as such:



**REVIEW:**

- A *bistable* multivibrator is one with *two* stable output states.
- In a bistable multivibrator, the condition of  $Q=1$  and  $\text{not-}Q=0$  is defined as *set*. A condition of  $Q=0$  and  $\text{not-}Q=1$  is conversely defined as *reset*. If  $Q$  and  $\text{not-}Q$  happen to be forced to the same state (both 0 or both 1), that state is referred to as *invalid*.
- In an S-R latch, activation of the S input sets the circuit, while activation of the R input resets the circuit. If both S and R inputs are activated simultaneously, the circuit will be in an invalid condition.
- A *race condition* is a state in a sequential system where two mutually-exclusive events are simultaneously initiated by a single cause.

Source: [http://www.allaboutcircuits.com/vol\\_4/chpt\\_10/2.html](http://www.allaboutcircuits.com/vol_4/chpt_10/2.html)