The 8259A is a device specifically designed for use in real time, interrupt driven microcomputer systems. It manages eight levels or requests and has built-in features for expandability to other 8259A’s (up to 64 levels). It is programmed by the system’s software as an I/O peripheral. A selection of priority modes is available to the programmer so that the manner in which the requests are processed by the 8259A can be configured to match his system requirements. The priority modes can be changed or reconfigured dynamically at any time during the main program. This means that the complete interrupt structure can be defined as required, based on the total system environment.

**INTERRUPT REQUEST REGISTER (IRR) AND IN-SERVICE REGISTER (ISR)**

The interrupts at the IR input lines are handled by two registers in cascade, the Interrupt Request Register (IRR) and the In-Service (ISR). The IRR is used to store all the interrupt levels which are requesting service; and the ISR is used to store all the interrupt levels which are being serviced.

**PRIORITY RESOLVER**
This logic block determines the priorities of the bits set in the IRR. The highest priority is selected and strobed into the corresponding bit of the ISR during INTA pulse.

**INTERRUPT MASK REGISTER (IMR)**

The IMR stores the bits which mask the interrupt lines to be masked. The IMR operates on the IRR. Masking of a higher priority input will not affect the interrupt request lines of lower quality.

**INT (INTERRUPT)**

This output goes directly to the CPU interrupt input. The VOH level on this line is designed to be fully compatible with the 8080A, 8085A and 8086 input levels.

**INTA (INTERRUPT ACKNOWLEDGE)**

INTA pulses will cause the 8259A to release vectoring information onto the data bus. The format of this data depends on the system mode (mPM) of the

**DATA BUS BUFFER**

This 3-state, bidirectional 8-bit buffer is used to interface the 8259A to the system Data Bus. Control words and status information are transferred through the Data Bus Buffer.

**READ/WRITE CONTROL LOGIC**

The function of this block is to accept output commands from the CPU. It contains the Initialization Command Word (ICW) registers and Operation Command Word (OCW) registers which store the various control formats for device operation. This function block also allows the status of the 8259A to be transferred onto the Data Bus.

**CS (CHIP SELECT)**

A LOW on this input enables the 8259A. No reading or writing of the chip will occur unless the device is selected.

**WR (WRITE)**

A LOW on this input enables the CPU to write control words (ICWs and OCWs) to the 8259A.

**RD (READ)**
A LOW on this input enables the 8259A to send the status of the Interrupt Request Register (IRR), In Service Register (ISR), the Interrupt Mask Register (IMR), or the Interrupt level onto the Data Bus.

A0

This input signal is used in conjunction with WR and RD signals to write commands into the various command registers, as well as reading the various status registers of the chip. This line can be tied directly to one of the address lines.

THE CASCADE BUFFER/COMPARATOR

This function block stores and compares the IDs of all 8259A’s used in the system. The associated three I/O pins (CAS0-2) are outputs when the 8259A is used as a master and are inputs when the 8259A is used as a slave. As a master, the 8259A sends the ID of the interrupting slave device onto the CAS0–2 lines. The slave thus selected will send its preprogrammed subroutine address onto the Data Bus during the next one or two consecutive INTA pulses. (See section “Cascading the 8259A.”)

INTERRUPT SEQUENCE

The powerful features of the 8259A in a microcomputer system are its programmability and the interrupt routine addressing capability. The latter allows direct or indirect jumping to the specific interrupt routine requested without any polling of the interrupting devices. The normal sequence of events during an interrupt depends on the type of CPU being used.

The events occur as follows in an MCS-80/85 system:

1. One or more of the INTERRUPT REQUEST lines (IR7–0) are raised high, setting the corresponding IRR bit(s).

2. The 8259A evaluates these requests, and sends an INT to the CPU, if appropriate.

3. The CPU acknowledges the INT and responds with an INTA pulse.

4. Upon receiving an INTA from the CPU group, the highest priority ISR bit is set, and the corresponding IRR bit is reset. The 8259A will also release a CALL instruction code (11001101) onto the 8-bit Data Bus through its D7–0 pins.

5. This CALL instruction will initiate two more INTA pulses to be sent to the 8259A from the CPU group.

6. These two INTA pulses allow the 8259A to release its preprogrammed subroutine address onto the Data Bus. The lower 8-bit address is released at the first INTA pulse and the higher 8-bit address is released at the second INTA pulse.
7. This completes the 3-byte CALL instruction released by the 8259A. In the AEOI mode the ISR bit is reset at the end of the third INTA pulse. Otherwise, the ISR bit remains set until an appropriate EOI command is issued at the end of the interrupt sequence.

The events occurring in an 8086 system are the same until step 4.

4. Upon receiving an INTA from the CPU group, the highest priority ISR bit is set and the corresponding IRR bit is reset. The 8259A does not drive the Data Bus during this cycle.

5. The 8086 will initiate a second INTA pulse. During this pulse, the 8259A releases an 8-bit pointer onto the Data Bus where it is read by the CPU.

6. This completes the interrupt cycle. In the AEOI mode the ISR bit is reset at the end of the second INTA pulse. Otherwise, the ISR bit remains set until an appropriate EOI command is issued at the end of the interrupt subroutine.

If no interrupt request is present at step 4 of either sequence (i.e., the request was too short in duration) the 8259A will issue an interrupt level 7. Both the vectoring bytes and the CAS lines will look like an interrupt level 7 was requested.

When the 8259A PIC receives an interrupt, INT becomes active and an interrupt acknowledge cycle is started. If a higher priority interrupt occurs between the two INTA pulses, the INT line goes inactive immediately after the second INTA pulse. After an unspecified amount of time the INT line is activated again to signify the higher priority interrupt wait can vary between parts. The designer should be aware of this consideration when designing a system which uses the 8259A. It is recommended that proper asynchronous design techniques be followed.

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